ODALYS BENITEZ

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EDUCATION

Olin College of Engineering Robotics Engineering

May 2022

SUMMARY

I'm a multidisciplinary engineer with a passion for developing and maintaining systems that drive positive global change. I have experience with software development, customer support, project management, and user-centered design. I'm looking to transition to a collaborative and user-focused role where I get to translate stakeholder needs into requirements, and bridge the gap between the human and the technical.

SKILLS

SOFTWARE DEVELOPMENT: Python, Linux Development, ROS2, Git, Docker, BigQuery, SQL, GCP MECHANICAL DESIGN: Solidworks, Onshape PROJECT MANAGEMENT: Notion, Jira, PowerBi, Agile Methodologies, Google Suite DESIGN SOFTWARE: Adobe Illustrator, Adobe Photoshop, Adobe Lightroom

EMPLOYMENT

RIGHTHAND ROBOTICS

Software Engineer II

- Working as a member of the Sustaining software team at a leading warehouse robotics automation company
- Performed debugging and root cause analysis for software, hardware, and electrical bugs on deployed robots
- Worked with stakeholders to better understand needs and pain points, translating into requirements for internal software teams
- Collaborated with internal software teams to implement and validate fixes for diagnosed issues
- Maintained close relationship with the Support team and Solutions team to ensure critical issues resolved in timely manner for the customer
- Integrated and merged new features/fixes into a large (>300 kLOC) Python codebase
- Utilized tools such as BigQuery SQL and PowerBi to assess and monitor robot performance KPIs

ELECTRIC BOAT

Undergraduate Research Opportunities Program

- Utilized stakeholder requirements to create a systems-level design for an ultra-high-precision underwater magnetic field probe
- Led meetings with client to ensure solution utility and fit throughout design process
- Created Python-based magnetometer calibration and verification routines
- Developed firmware for an STM32-based platform to read and fuse multiple sensors to achieve orientation-corrected magnetic field readings

MACHINA LABS

Robotics Engineering Intern

- Diagnosed timing and loop overrun bugs in a real-time robotic controls application
- Integrated new production functionality into a mature codebase
- Implemented kernel-level configuration to optimize Python-based control loop jitter
- Used multithreading to parallelize runtime objectives and increase code performance

NASA-FUNDED ASTEROID DISCOVERY RESEARCH

Research Assistant

- Worked under Dr. Carrie Nugent to build a software pipeline to discover near-Earth asteroids in archival data
- Addressed complex parameter optimization issues by creating Python scripts for image processing and modification

PROJECTS

SUN-TRACKING SOLAR ARRAY AT WOODLAND HARVEST MOUNTAIN FARM

- Developed 2 DoF pan/tilt mechanism for sun-tracking of a 1kW, 300 lb solar array
- Created control loops to actuate motors for desired array orientation
- Utilized pyranometer and accelerometer sensor data for active sun-tracking and orientation determination

OLIN COLLEGE OF ENGINEERING CAPSTONE

- Developed OAE device from scratch for affordable infant hearing screening in Latin America
- Constructed analog filters for audio signal processing
- Designed PCB adapter with microphone amplification to fit inside OAE probe

June 2022 to July 2024

Sept. 2021 to May 2022

June 2021 to Sept. 2021

Jan. 2020 to Sept. 2020

Sept. 2020 to May 2021

Aug. 2021 to May 2022